

## TIMS-0201 USB SINGLE AXIS STEPPER MOTOR CONTROLLER

#### **HIGHLIGHTS**

**USB Interface** 

**Upgradeable Firmware** 

Home, Forward Limit,

**Reverse Limit Inputs** 

**Adjustable Current Level** 

**Quadrature Encoder Inputs** 

Motor Voltage and Current Measurement

**Thermal Overload Protection** 

Accepts 10 - 40 Volt, up to 2A, Power Supply

Half-Step and Full-Step Capability

General Purpose I/O Pins (DIO,AI,T/C,PWM)

Bipolar Constant Current Motor Drive with Wide Range of Programmable Current Control 5-1000 mA

Fast Recovery Schottky Commutation Diodes

## **TIMS-0201**

## STEPPER MOTOR CONTROLLER

## **USB - SINGLE AXIS**

# Industry-leading Command of Stepping Motors

Jova Solutions TIMS-0201™ single axis stepper motor controllers are low cost "plug and play" solutions for operating small to midsize stepping motors. A USB interface, now standard on all PCs and laptops, eliminates the need for PCI plug-in cards and costly installations. The USB 1.1/2.0 full speed interface allows you to rapidly connect, disconnect and move the TIMS-0201 module without needing a time consuming installation or computer reboot.

The TIMS-0201 stepper motor controller contains general purpose I/O pins with software configurable functionality including digital input, digital output, counter/timer input, PWM output or analog input. The GPIO pins can also be programmed to be home, reverse or forward limit switch inputs or quadrature encoder inputs.

#### **Stepper Motor Commands**

The TIMS-0201's stepper motor controllers on-board programmable controller provides step output signals to the driver circuits. A 32-bit position register tracks motor position using internal counts or the optional encoder inputs. The TIMS-0201 library of commands provide flexibilty and programming ease.

#### **Input Signals**

Home, CW and CCW Limits, and quadrature encoder inputs are available for each motor.

#### **Stepper Motor Interface Outputs**

There are six output lines for direct connection to the stepper motor. Winding motors A and B each have Phase A, Phase B, and Center Tap outputs.

## **USB** Interface

The TIMS-0201 modules interface to computers via a USB 1.0/2.0 full speed (FS) connection.
USB connections allow a virtually unlimited number of USB devices to connect through a single PC port.

#### **Drivers and Software**

A complete LabVIEW driver library is provided for ease of integration into higher level programs. A low-level DLL is also provided for integration with other programming languages. All drivers are available for both the Windows and Linux operating systems.

#### **Power Supply**

Each TIMS-0201 stepper motor controller has a 2.1 mm connector that accepts power from an external +10 to +40 Vdc power supply. USB provides 5-volt power to the on-board logic circuitry.



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#### **TIMS-0201 Commands**

Position	Move	Seek	
Read/Set Step Count	Get/Set Step Rate	Set/Get Seek Step Rate	
Read/Set Encoder Count	Move Absolute/Relative	Seek Home	
Get Target Position	Move Continuos	Seek Forward/Reverse Limit	
Enable/Disable Encoder	Single Step	Get/Set Soft Limits	
	Stop		
GPIO .	Motor		
Get/Set GPIO Configuration	Get/Set Motor Current Limit		
Read/Write DIO	Get Motor Status		
Set/Read Timer/Counter	Read Motor Winding Voltage +		
Get/Set PWM			

## **TIMS-0201 Summary Chart**

Motor Type Supported	2-Phase
Axes	1
Max Amps/Phase	1.0
Step Rate Maximum	4000 Steps/sec
Resolution (Steps)	1/2 or Full
Programmable Current	Yes
Limit Switch Support	Yes
Quadrature Encoder Inputs	Yes
General Purpose I/O - Pins	6

## **Physical Specifications**

Operating Temperature	0 to +50 deg C.		
Storage Temperature	– 40 deg C to +125 deg C		
Temperature (max)	+70 deg C		
Height	1.30 (in.)		
Width	4.00 (in.)		
Depth	3.00 (in.)		
Weight	7 oz.		

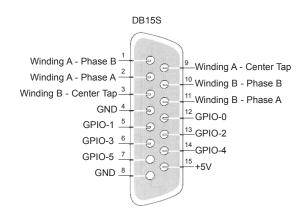
## **TIMS-0201 Stepper Motor Controller General Purpose IO**

GPIO	DI	DO	ΑI	Quad Encoder	Timer Counter	PWM	Home Limit	FWD Limit	REV Limit
0	✓	✓		✓			✓	✓	✓
1	✓	✓		✓			✓	✓	✓
2	✓	✓					✓	✓	✓
3	✓	✓			✓		✓	✓	✓
4	✓	✓	✓			✓	✓	✓	✓
5									_

## **Stepper Motor Interface Connector (DB-15S) Pin Out**

## Pin Signal

1	Winding A - Phase B
2	Winding A - Phase A
3	Winding B - Center Tap
4	GND
5	GPIO-1
6	GPIO-3
7	GPIO-5
8	GND
9	Winding A - Center tap
10	Winding B - Phase B
11	Winding B - Phase A
12	GPIO-0
13	GPIO-2
14	GPIO-4
15	+5V
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